ORDER AND CONVERGENCE OF THE ENHANCED 3-POINT FULLY IMPLICIT SUPER CLASS OF BLOCK BACKWARD DIFFERENTIATION FORMULA FOR SOLVING INITIAL VALUE PROBLEM

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ABSTRACT
This paper studied an enhanced 3-point fully implicit super class of block backward differentiation formula for solving stiff initial value problems developed by Abdullahi & Musa and go further to established the necessary and sufficient conditions for the convergence of the method. The method is zero stable, A-stable and it is of order 5. The method is found to be suitable for solving first order stiff initial value problems.

Keyword: A-Stable, Block, Consistency, Convergence, Order and Zero stability

INTRODUCTION
In science, engineering and social science most of the real life problems are converted into models. Such models brought stiff ordinary differential equations. Block backward differentiation formula is one of the reliable block numerical methods for obtaining solutions of stiff initial value problems. Backward differentiation formula was first discovered by Curtis and Hirschfelder (1952), in his method integration of stiff equations, Cash (1980) extended the work of Curtiss, with integration of stiff system of ODEs using extended backward differentiation formula, Milner (1953) discovered block numerical solution of differential equation, Brugano (1998) with solving differential problem by multistep method, Chu and Hamilton (1987) with parallel solution of ODE’s by multistep method, Dalquish (1974) with problem related to numerical method, Ibrahim (2007) developed 2 and 3 point implicit methods for solving stiff initial value problem, both methods are zero and A-stable can handle stiff problem with appreciated results. Among the

\[ \sum_{i=0}^{\alpha} q_{i,j} y_{n+j-2} = \beta_{k,i} (f_{n+k} - \rho f_{n+k-1}), k = 1, 2, 3 \]  

A non-zero coefficient \( \beta_{k-2,1} \neq 0 \) was introduced in (1) (where \( \beta_{k-2,1} = \rho \beta_{k,i} \)) and a free parameter \( \rho \) was choosing as \( \rho = -\frac{4}{5} \) to obtains the 3ESBBDF formula

\[ \sum_{i=0}^{\alpha} q_{i,j} y_{n+j-2} = \beta_{k,i} (f_{n+k} - \rho f_{n+k-2}) k = 1, 2, 3 \]  

Using \( \rho = -\frac{4}{5} \) the following method was derived

\[ y_{n+1} = -\frac{29}{70}y_{n-2} + \frac{37}{28}y_{n-1} + \frac{9}{7}y_{n} + \frac{27}{140}y_{n+2} - \frac{27}{140}y_{n+3} - \frac{15}{70}f_{n+1} + \frac{12}{7}f_{n-1} \]  

\[ y_{n+2} = -\frac{22}{405}y_{n-2} + \frac{44}{315}y_{n-1} + \frac{124}{315}y_{n} + \frac{124}{315}y_{n+1} - \frac{66}{105}y_{n+2} + \frac{1}{10}f_{n} + \frac{1}{2}f_{n+2} \]

\[ y_{n+3} = \frac{68}{705}y_{n-2} + \frac{92}{705}y_{n-1} + \frac{124}{315}y_{n} - \frac{116}{315}y_{n+1} + \frac{128}{705}y_{n+2} + \frac{1}{210}f_{n+1} + \frac{1}{42}f_{n+3} \]

(3) is called Enhanced 3-Point fully implicit super class of block backward differentiation formula for solving first initial value problems.

Detailed of derivation and stability analysis of the method can found in (Abdullahi & Musa 2021)
Order of the Method

In this section, we derive the order of the methods (3) for the values of \( \rho = -\frac{4}{5} \).

The method (3) can be converted to a general matrix form as follows

\[
\sum_{j=0}^{m} C_j y_{m+1-j} = h \sum_{j=0}^{m} D_j y_{m+1-j}. \tag{4}
\]

Where \( C_0, C_1, D_0 \) and \( D_1 \) are square matrices defined by

\[
C_0 = \begin{bmatrix}
29 & 37 & -9 & 27 \\
70 & 28 & 44 & 53 \\
27 & 44 & 44 & 53 \\
68 & 435 & 1240 & 673
\end{bmatrix}, \quad C_1 = \begin{bmatrix}
1 & -23 & 27 \\
72 & 53 & 1 & 265 \\
1580 & 1380 & 673 & 1
\end{bmatrix} \tag{5}
\]

\[
D_0 = \begin{bmatrix}
0 & 12 & 0 & 0 \\
0 & 0 & 48 & 0 \\
0 & 0 & 0 & 0 \\
\end{bmatrix}, \quad D_1 = \begin{bmatrix}
\frac{15}{7} & 0 & 0 & 0 \\
0 & \frac{60}{53} & 0 & 0 \\
\frac{48}{673} & 0 & \frac{300}{673} & 0
\end{bmatrix} \tag{6}
\]

and \( y_{m-1}, y_{m-2} \) and \( f_m \) are column vectors defined by

\[
y_m = \begin{bmatrix}
y_{n+1} \\
y_{n+2} \\
y_{n+3}
\end{bmatrix}, \quad y_{m-1} = \begin{bmatrix}
y_{n-2} \\
y_{n-1} \\
y_n
\end{bmatrix}, \quad f_{m-1} = \begin{bmatrix}
f_{n-2} \\
f_{n-1} \\
f_n
\end{bmatrix}, \quad f_m = \begin{bmatrix}
f_{n+1} \\
f_{n+2} \\
f_{n+3}
\end{bmatrix}
\]

Thus, equations (3) can be rewritten as

\[
\begin{bmatrix}
29 & 37 & -9 & 27 \\
70 & 28 & 44 & 53 \\
27 & 44 & 44 & 53 \\
68 & 435 & 1240 & 673
\end{bmatrix}
\begin{bmatrix}
y_{n-2} \\
y_{n-1} \\
y_n \\
y_{n+1}
\end{bmatrix} + \begin{bmatrix}
1 & -23 & 27 \\
72 & 53 & 1 & 265 \\
1580 & 1380 & 673 & 1
\end{bmatrix}
\begin{bmatrix}
y_{n+1} \\
y_{n+2} \\
y_{n+3}
\end{bmatrix} = h \begin{bmatrix}
0 & 12 & 0 & 0 \\
0 & 0 & 48 & 0 \\
\frac{15}{7} & 0 & 0 & 0
\end{bmatrix}
\begin{bmatrix}
y_{n+1} \\
y_{n+2} \\
y_{n+3}
\end{bmatrix} + h \begin{bmatrix}
0 & \frac{60}{53} & 0 & 0 \\
\frac{68}{673} & 0 & \frac{300}{673} & 0
\end{bmatrix}
\begin{bmatrix}
y_{n+1} \\
y_{n+2} \\
y_{n+3}
\end{bmatrix} \tag{7}
\]

Let \( C_0^*, C_1^* \) and \( D_0^* \) be block matrices defined by

\[
C_0^* = [C_0, C_1, C_2], \quad C_1^* = [C_3, C_4, C_5], \quad D_0^* = [D_0, D_1, D_2]
\]

\[
D_1^* = [D_3, D_4, D_5].\text{Where}
\]

\[
C_0 = \begin{bmatrix}
27 & 53 & -7 & 53 \\
265 & 435 & 1240 & 673
\end{bmatrix}, \quad C_1 = \begin{bmatrix}
37 & 44 & 44 & 53 \\
435 & 1240 & 673 & 673
\end{bmatrix}, \quad C_2 = \begin{bmatrix}
-9 & 53 & 53 & 53 \\
53 & 1 & 265 & 673
\end{bmatrix}, \quad C_3 = \begin{bmatrix}
-23 & 27 & 27 & 27 \\
72 & 53 & 1 & 265 \\
1580 & 1380 & 673 & 1
\end{bmatrix}
\]

\[
D_0 = \begin{bmatrix}
0 & 12 & 0 & 0 \\
0 & 0 & 48 & 0 \\
\frac{15}{7} & 0 & 0 & 0
\end{bmatrix}, \quad D_1 = \begin{bmatrix}
0 & \frac{60}{53} & 0 & 0 \\
\frac{68}{673} & 0 & \frac{300}{673} & 0
\end{bmatrix}, \quad D_2 = \begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix} \tag{8}
\]

**Definition** (Order of the Method): The order of the block method (3) and its associated linear operator are given by

\[
L(y(x); h) = \sum_{i=0}^{p} [C_i y(x + jh)] - h \sum_{i=0}^{p} [D_i y'(x + jh)] \tag{10}
\]

Where \( p \) is unique integer such that

\[
E_q = 0, \quad q = 0, 1, ... \quad \text{and} \quad E_{p+1} \neq 0, \text{where the} \quad E_q \text{are constant Matrices}
\]

Defined by:

\[
E_q = C_0 + C_1 + \ldots + C_q
\]

\[
E_{p+1} = C_0 + C_1 + C_2 + \ldots + k C_k - (D_0 + D_1 + \ldots + D_k)
\]

\[
E_q = \frac{1}{q!} (C_0 + 2q C_2 + \ldots + k^q C_k) - \frac{1}{(q-1)!} (D_1 + 2q^{q-1} D_2 + \ldots + (k)q^{q-1} D_k).
\]

For \( q = 0 \), we have

\[
E_0 = C_0 + C_1 + C_2 + C_3 + C_4 + C_5
\]

\[
= \begin{bmatrix}
29 & 27 & 265 & -2 & -2 & 27 \\
70 & 28 & 84 & 44 & 53 & 28 \\
27 & 44 & 44 & 44 & 53 & 53 \\
68 & 435 & 435 & 1240 & 673 & 673
\end{bmatrix} + \begin{bmatrix}
1 & -23 & 27 \\
72 & 53 & 1 & 265 \\
1580 & 1380 & 673 & 1
\end{bmatrix} = \begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix} \tag{11}
\]
\[ E_1 = C_1 + 2C_2 + 3C_3 + 4C_4 + 5C_5 - (D_0 + D_1 + D_2 + D_3 + D_4 + D_5) \]
\[
= \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2 \begin{bmatrix} -9 \\ -23 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 5 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (12)

\[ E_2 = \frac{1}{2!}(C_1 + 2^2C_2 + 3^2C_3 + 4^2C_4 + 5^2C_5) - \frac{1}{2!}(D_1 + 2D_2 + 3D_3 + 4D_4 + 5D_5) \]
\[
= \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2^2 \begin{bmatrix} -9 \\ -22 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3^2 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 4^2 \begin{bmatrix} 27 \\ 14 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 5^2 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (13)

\[ E_3 = \frac{1}{3!}(C_1 + 2^3C_2 + 3^3C_3 + 4^3C_4 + 5^3C_5) - \frac{1}{3!}(D_1 + 2^3D_2 + 3^3D_3 + 4^3D_4 + 5^3D_5) \]
\[
= \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2^3 \begin{bmatrix} -9 \\ -22 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3^3 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 4^3 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 5^3 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (14)

\[ E_4 = \frac{1}{4!}(C_1 + 2^4C_2 + 3^4C_3 + 4^4C_4 + 5^4C_5) - \frac{1}{4!}(D_1 + 2^4D_2 + 3^4D_3 + 4^4D_4 + 5^4D_5) \]
\[
= \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2^4 \begin{bmatrix} -9 \\ -22 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3^4 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 4^4 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 5^4 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (15)

\[ E_5 = \frac{1}{5!}(C_1 + 2^5C_2 + 3^5C_3 + 4^5C_4 + 5^5C_5) - \frac{1}{5!}(D_1 + 2^5D_2 + 3^5D_3 + 4^5D_4 + 5^5D_5) \]
\[
= \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2^5 \begin{bmatrix} -9 \\ -22 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3^5 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 4^5 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 5^5 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (16)

\[ E_6 = \frac{1}{6!}(C_1 + 2^6C_2 + 3^6C_3 + 4^6C_4 + 5^6C_5) - \frac{1}{6!}(D_1 + 2^6D_2 + 3^6D_3 + 4^6D_4 + 5^6D_5) = \begin{bmatrix} 37 \\ 28 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 2^6 \begin{bmatrix} -9 \\ -22 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 3^6 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 4^6 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + 5^6 \begin{bmatrix} 27 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}
\] (17)
Therefore, the method (3) is of order 5 according to definition (1), with error constant as $E_d = \begin{bmatrix} \frac{-17}{10} \\ \frac{12}{5} \end{bmatrix}$

Convergence of the Method
In this section, we apply the theorem on convergence by Henrici (1962) to show the convergence of the method (3)

Theorem (1): Henrici (1962) stated the following conditions for convergence of Linear Multi-Step Method (LMM):
1. A necessary condition for convergence of the Linear Multi-step Method (3) is that the modulus of none of the root of the associated polynomial $\rho(\xi)$ exceeds one, and that the roots of modulus one is simple. The condition, thus imposed on $\rho(\xi)$ is called the condition of zero stability.
2. A necessary condition for convergence of the Linear Multi-step Method (3) is that the order of the associated difference operator be at least one. The condition that the order $p \geq 1$, is called the condition of consistency.

To prove that the method (3) is convergent, we need to show that conditions (1) and (2) stated in Theorem (1) are satisfied.

Stability Analysis of the Method
Consider the 3-point super class of block backward differentiation formula derived in (3)

Definition 2 (Zero Stability)
A linear Multistep method (3) is said to be zero stable if no root of the first characteristic polynomial has modulus greater than one and that any root with modulus one is simple.

The characteristic polynomial of the method (3) is given by:

$$R(t, \tilde{h}) = \det(A + t - B) = 0$$

Where Det. stands for the determinant. Thus,

$$R(t, \tilde{h}) = \begin{vmatrix} \frac{-1074666933}{1257254257} & \frac{-267544415}{6688694} & \frac{3343095}{5826389007} \\ \frac{-89250}{128627} & \frac{-297613352}{61869587} & \frac{-25020464}{24759199} \\ \frac{1257254257}{128627} & \frac{5826389007}{61869587} & \frac{43247478348}{249683} \end{vmatrix} = 0$$

(20)

By putting $\tilde{h} = h\lambda = 0$ in (20), we obtain the first characteristic polynomial as:

$$R(t, 0) = \begin{vmatrix} \frac{-1074666933}{1257254257} & \frac{-267544415}{6688694} & \frac{3343095}{5826389007} \\ \frac{-89250}{128627} & \frac{-297613352}{61869587} & \frac{-25020464}{24759199} \\ \frac{1257254257}{128627} & \frac{5826389007}{61869587} & \frac{43247478348}{249683} \end{vmatrix} = 0$$

(21)

Hence $t = 1, \ t = 0.4554548367$ and $t = -0.027686857$

Therefore, the method (3) is Zero Stable according to definition (2).

Consistency Conditions
Definition 3 (Consistency)
A Linear Multi-Step Method is said to be consistent if its order $p$ is greater than or equal to one. It also follows that a LMM is consistent if and only if:

$$\sum_{k=0}^{p} C_j = 0$$

(23)

and

$$\sum_{k=0}^{p} jC_j = \sum_{j=0}^{p} D_j$$

(24)

Where $C_j$ and $D_j$ are constant coefficient matrices. Similarly, it follows that LMM is consistent if and only if $\rho(1) = 0$ and $\rho(1) = \sigma(1)$. Where $\rho$ and $\sigma$ are the first and second characteristic polynomial respectively.

In this previous section, it has been shown that the method (3) is of order 5, which is greater than 1, that is order $p \geq 1$

Thus, the linear multi-step method (3) is consistent if the Conditions (23) and (24) stated above are satisfied:

$$\sum_{j=0}^{5} C_j = C_0 + C_1 + C_2 + C_3 + C_4 + C_5$$

$$= \begin{bmatrix} 29 \\ 70 \\ 27 \\ 68 \\ 27 \\ 673 \end{bmatrix} + \begin{bmatrix} 37 \\ 28 \\ 44 \\ 435 \\ 52 \\ 673 \end{bmatrix} + \begin{bmatrix} -9 \\ 7 \\ 44 \\ 1240 \\ 53 \\ 673 \end{bmatrix} + \begin{bmatrix} 1 \\ 72 \\ 53 \\ 1580 \\ 1380 \\ 673 \end{bmatrix} + \begin{bmatrix} -23 \\ 14 \\ -23 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 27 \\ 140 \\ 68 \\ 53 \\ 265 \\ 673 \end{bmatrix} = 0$$

(25)

Therefore, the condition (23) is satisfied. Also

$$\sum_{j=0}^{5} jC_j = 0 \cdot C_0 + 1 \cdot C_1 + 2 \cdot C_2 + 3 \cdot C_3 + 4 \cdot C_4 + 5 \cdot C_5$$

Therefore, the method (3) is consistent.
\[
\begin{align*}
&= 0 \cdot \begin{bmatrix} 29 \\ 70 \\ 27 \\ 22 \\ 35 \\ 23 \\ 36 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 1 \cdot \begin{bmatrix} 37 \\ 44 \\ 53 \\ 53 \\ 1240 \\ 1240 \\ 1580 \\ 1580 \\ 1580 \end{bmatrix} + 2 \cdot \begin{bmatrix} -9 \\ 7 \\ 53 \\ 53 \\ 673 \\ 673 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 3 \cdot \begin{bmatrix} 1 \\ 72 \\ 53 \\ 53 \\ 673 \\ 673 \\ 673 \\ 673 \\ 673 \end{bmatrix} + 4 \cdot \begin{bmatrix} -23 \\ 14 \\ 108 \\ 108 \\ 265 \\ 265 \\ 265 \\ 265 \\ 265 \end{bmatrix} + 5 \cdot \begin{bmatrix} 27 \\ 140 \\ 53 \\ 53 \\ 368 \\ 368 \\ 368 \\ 368 \\ 368 \end{bmatrix} = \begin{bmatrix} -27 \\ 108 \\ 53 \\ 53 \\ 368 \\ 368 \\ 368 \\ 368 \\ 368 \end{bmatrix} \quad (26)
\end{align*}
\]

And

\[
\sum_{j=0}^{5} D_j = D_0 + D_1 + D_2 + D_3 + D_4 + D_5
\]

\[
= \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -12 \\ 7 \\ 48 \\ 53 \\ 60 \\ 368 \\ 673 \\ 673 \end{bmatrix} + \begin{bmatrix} 15 \\ 7 \\ 60 \\ 53 \\ 673 \\ 673 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 48 \\ 53 \\ 673 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 60 \\ 53 \\ 673 \end{bmatrix} = \begin{bmatrix} -27 \\ -7 \\ 108 \\ 53 \\ 368 \\ 673 \end{bmatrix} \quad (27)
\]

Therefore, \( \sum_{j=0}^{5} C_j = \sum_{j=0}^{5} D_j \), Thus, condition in (24) is met; the method (3) is consistent. Hence, the method (3) is Convergent in accordance with the theorem (1)

**CONCLUSION**

All the necessary and sufficient conditions for the convergence of a linear Multistep Method has been tested in this paper on the developed method, Enhanced 3-Point fully implicit block backward differentiation formula and the method satisfied the conditions. The order of the method has been investigated; the method is of order 5. This is found to be suitable for solving first order stiff initial value problems (IVPs).

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